

# Curves in Surfaces and the Mapping Class Group

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# Introduction and Definition

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- Surface

Intuition: objects such that they resemble  $\mathbb{R}^2$  when  
“zoomed in.”

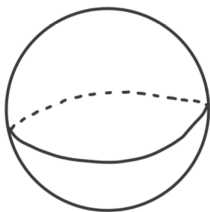
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(a) Sphere

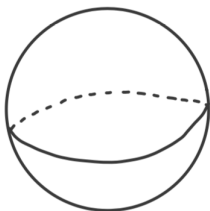
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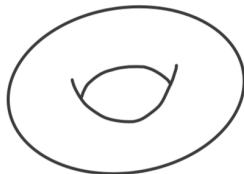
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(a) Sphere



(b) Torus

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- Symmetry  
Intuition: repeated sameness.

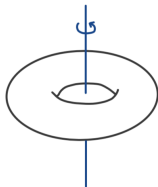
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## ■ Symmetry

Intuition: repeated sameness.



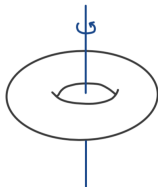
**Figure:** Example of symmetry: rotate  $\pi$  counterclockwise

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- Symmetry  
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**Figure:** Example of symmetry: rotate  $\pi$  counterclockwise

- Homeomorphism  
Continuous bijection with continuous inverse.

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- Curve

Intuition: mark on a surface that helps us study symmetries.



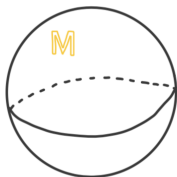
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(a) Example of curve on sphere

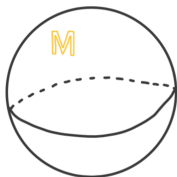
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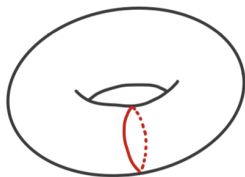
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(a) Example of curve on sphere



(b) Example of curve on torus

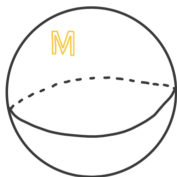
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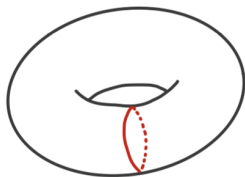
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## ■ Curve

Intuition: mark on a surface that helps us study symmetries.



(a) Example of curve on sphere



(b) Example of curve on torus

Note: We study *closed* curves, which are images of circles under homeomorphisms.

# History and Motivation

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- Dehn [1920s]

$$\text{Homeo}^+(S) \rightsquigarrow \text{Mod}(S)$$

- $\text{Homeo}^+(S)$ : The set of orientation-preserving homeomorphisms that map  $S$  to  $S$ .

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- “Sameness”: Two homeomorphisms are the “same” if for every curve in the domain, the image of the curve under one homeomorphism can be “wiggled” into the image of another.

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- “Sameness”: Two homeomorphisms are the “same” if for every curve in the domain, the image of the curve under one homeomorphism can be “wiggled” into the image of another.
- $\text{Mod}(S)$ : The “mapping class group” of  $S$ .

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- Nielson & Thurston  
Classified  $S$  into three types of elements:

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- Nielson & Thurston

Classified  $S$  into three types of elements:

- 1 Finite-order elements
- 2 Reducible elements
- 3 Pseudo-Anosov maps



# Classification

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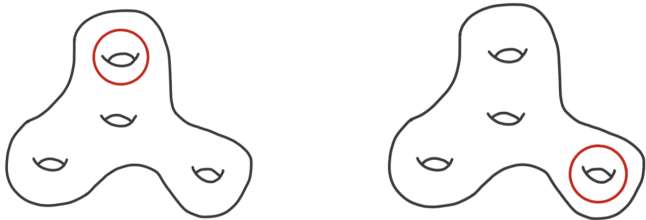
- Finite-order elements  
*Some power fixes all curves.*

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**Figure:** Example of a finite order element: rotate clockwise by  $2\pi$

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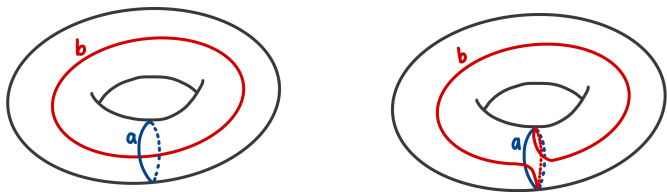
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- Reducible elements  
*Every power fixes some curve.*



**Figure:** Example of reducible element: Dehn twist

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- Pseudo-Anosov maps  
*No power fixes any curve.*

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- Pseudo-Anosov maps  
*No power fixes any curve.*



**Figure:** Too complicated to display

# Motivation and Project Goals

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- Standard construction for pseudo-Anosov maps from  $S$  to  $S$  – *Penner's Construction*

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- Standard construction for pseudo-Anosov maps from  $S$  to  $S$  – *Penner's Construction*
- There exist constructions of pseudo-Anosov maps that do not come from Penner's Construction or its powers.



# Motivation and Project Goals

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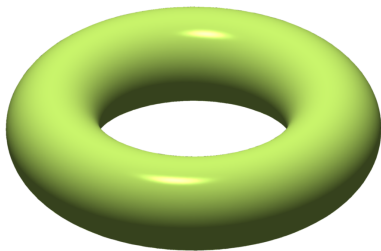
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- Standard construction for pseudo-Anosov maps from  $S$  to  $S$  – *Penner's Construction*
- There exist constructions of pseudo-Anosov maps that do not come from Penner's Construction or its powers.
- Our goal: visualizing and understanding these new constructions. Trying to create new constructions of pseudo-Anosov maps.

# A Torus

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**Figure:** A Torus (Retrieved from <https://en.wikipedia.org>)

# A Connected Sum of Two Tori

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**Figure:** A Connected Sum of Two Tori (Retrieved from <https://en.wikipedia.org>)

# Classification of Surfaces

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## Theorem

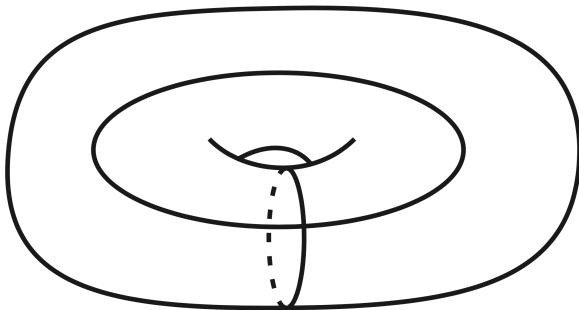
*Every orientable compact surface is homeomorphic to a sphere or a connected sum of tori.*



# Dehn Twist

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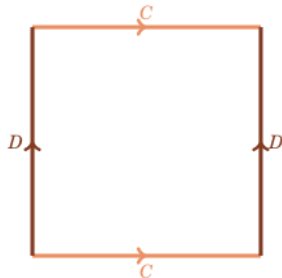
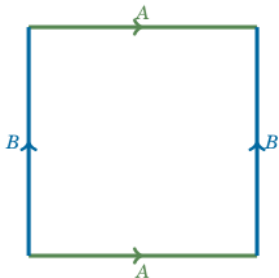


**Figure:** (Retrieved from *Office Hours with a Geometric Group Theorist* by Matt Clay and Dan Margalit)

# Polygonal Representation of a Torus

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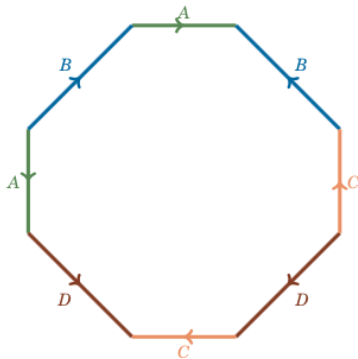


**Figure:** Polygonal Representation of a Torus (Retrieved from <https://math.stackexchange.com>)

# Polygonal Representation of a Connected Sum of Two Tori

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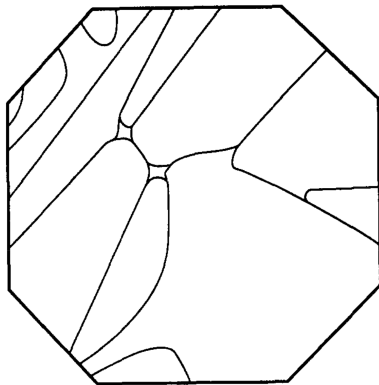


**Figure:** A Connected Sum of Two Tori (Retrieved from <https://math.stackexchange.com>)

# Dehn Twist in Polygonal Representation

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**Figure:** A pseudo-Anosov map that is a Composition of Dehn Twists  
(by M. Bestvina and M.Handel)

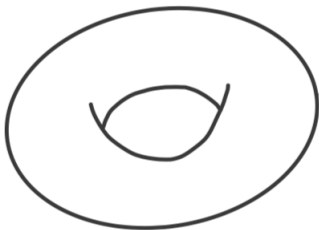


# Linear Algebra and $\text{Mod}(S)$

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- Elements of  $\text{Mod}(S)$  have matrix representations
- e.g.  $\text{Mod}(T^2) \cong SL_2(\mathbb{Z})$ .



**Figure:**  $T^2 = \text{Torus}$

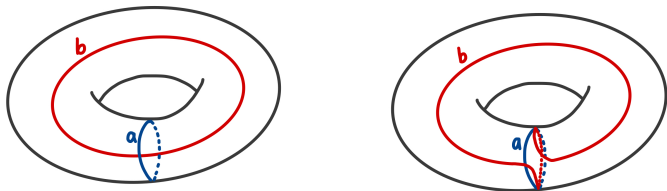
# Linear Algebra and $\text{Mod}(S)$

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- Convert curves to a graph
- Can think of curves  $a$  and  $b$  as a “basis”
- Get matrix representations of Dehn twists about  $a$  and  $b$ , respectively:

- $[T_a] = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  and  $[T_b] = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$



**Figure:** Dehn twist about  $a$

# Linear Algebra and Mod( $S$ )

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If we consider,  $A = [T_a][T_b] = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$ , then  $A$  has eigenvalues  $\lambda_1 = \frac{3+\sqrt{5}}{2}$  and  $\lambda_2 = \frac{3-\sqrt{5}}{2} = 1/\lambda_1$ , with corresponding eigenvectors  $v_1 = \begin{bmatrix} \frac{1+\sqrt{5}}{2} \\ 1 \end{bmatrix}$  and  $v_2 = \begin{bmatrix} \frac{1-\sqrt{5}}{2} \\ 1 \end{bmatrix}$ , respectively.

# Linear Algebra and $\text{Mod}(S)$

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- So  $A$  stretches a direction  $v_1$  by the factor  $\lambda_1$ , and it squeezes another direction  $v_2$  by  $\lambda_2 = 1/\lambda_1$ .
- This is an example of a pseudo-Anosov map!
- Every pseudo-Anosov exhibits this property

# Which One?

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- Elements of  $\text{Mod}(S)$  are called classes and denoted  $[f]$ , where  $[f] := \{\text{homeos that are the "same" as } f\}$ .
- Q: Given a class  $[f] \in \text{Mod}(S)$ , what is the "best" element in the class to analyze?
- A: The one whose matrix representation has the lowest eigenvalues!

# Bestvina-Handel

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The Bestvina-Handel algorithm will find the “best” representation of a class for us!

- Lowers eigenvalues to find the best map
- Does so by changing the graph of the image of a curve
- Examples: Valence 2 isotopy, folding, and subdivision

# What's Next?

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Tasks/questions yet to be completed/answered

- Use the Bestvina-Handel algorithm to study the maps given by Penner's construction
- How do new constructions of pseudo-Anosov maps differ from Penner's, and why do they give different pseudo-Anosov maps?
- Compute the stretch factor of a pseudo-Anosov map from a different construction. Does it differ from that of Penner.
- Can we create a new construction?

# References

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